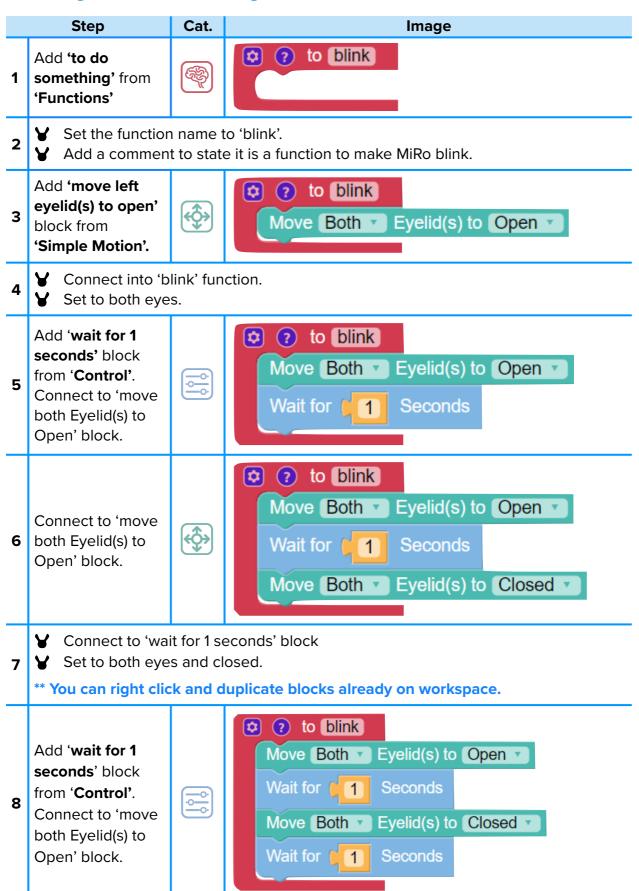
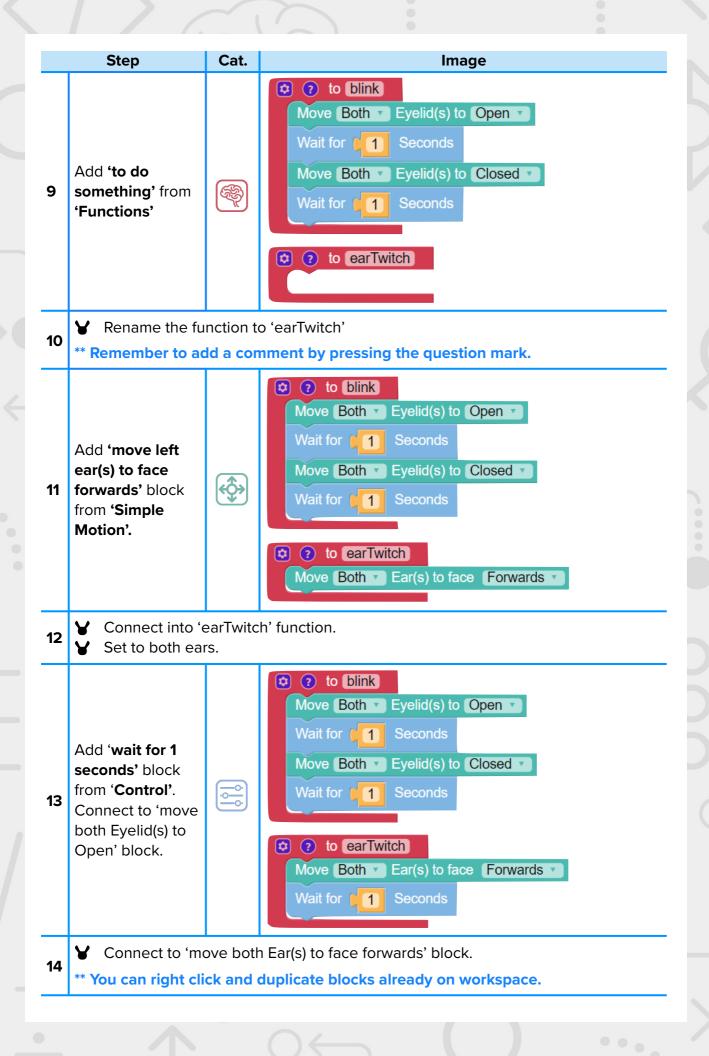
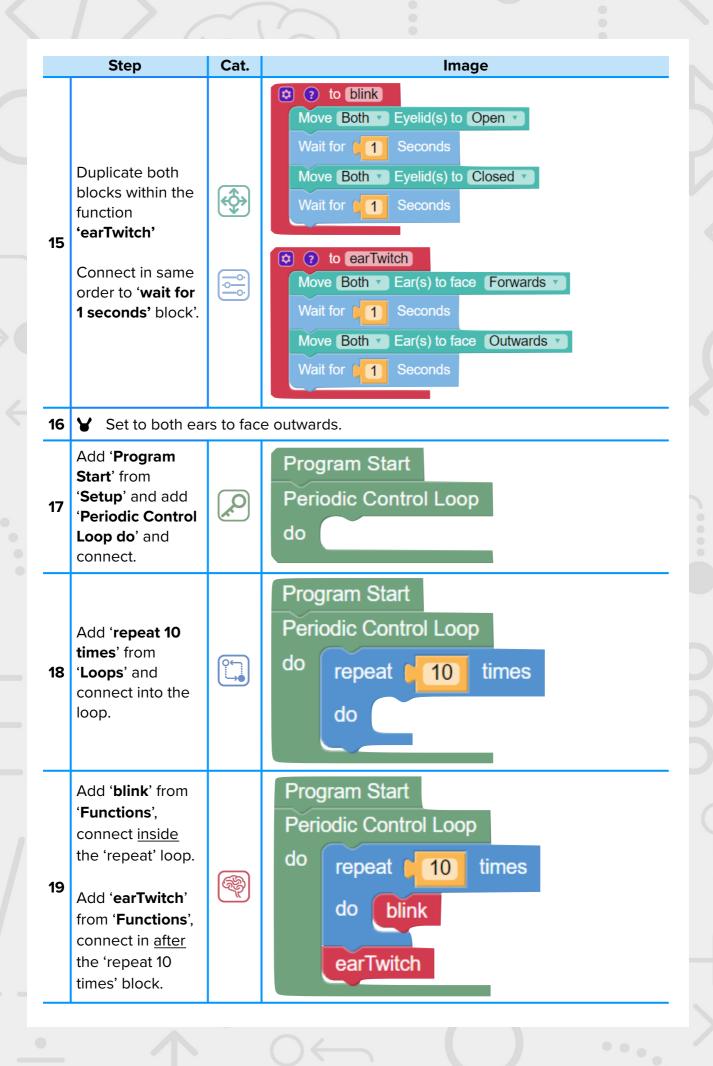
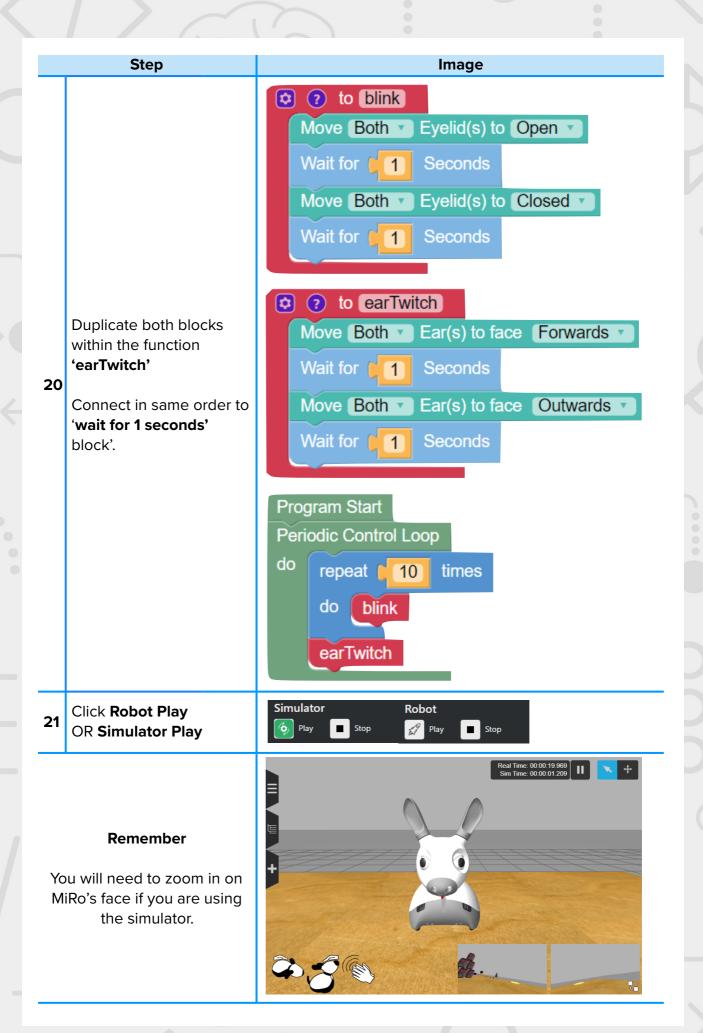
## PART 1 Step-by-Step - Create two functions to control MiRo's blinking and ear twitching.

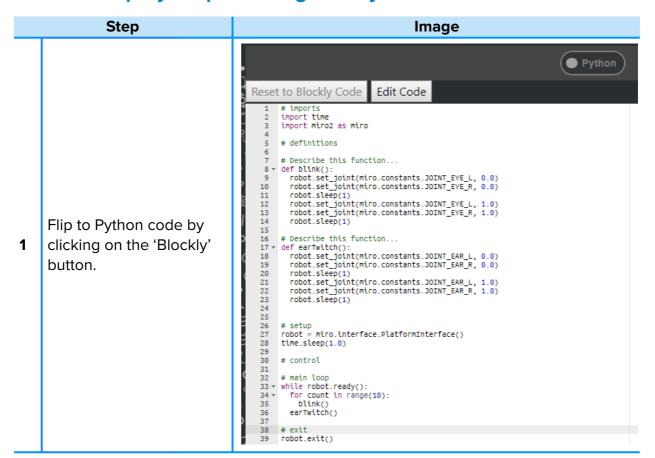








## PART 2 Step-by-Step - Moving into Python



Can you find the two functions?

What code defines a function?

2	Locate the lines in each function that control the time between actions.	robot.sleep(1)
3	Edit the time set within the code from '1' to '0.5'.	16 # Describe this function 17 v def earTwitch(): 18 robot.set_joint(miro.constants.JOINT_EAR_L, 0.0) 19 robot.set_joint(miro.constants.JOINT_EAR_R, 0.0) 20 robot.sleep(0.5)
	There are 4 locations to edit, 2 in each function.	robot.set_joint(miro.constants.JOINT_EAR_L, 1.0) robot.set_joint(miro.constants.JOINT_EAR_R, 1.0) robot.sleep(0.5)

## Run your program

**4** Experiment with the settings and investigate:

Change the time further up and down to observe the change in output.